

SON Coordination for parameter conflict resolution: A reinforcement learning framework

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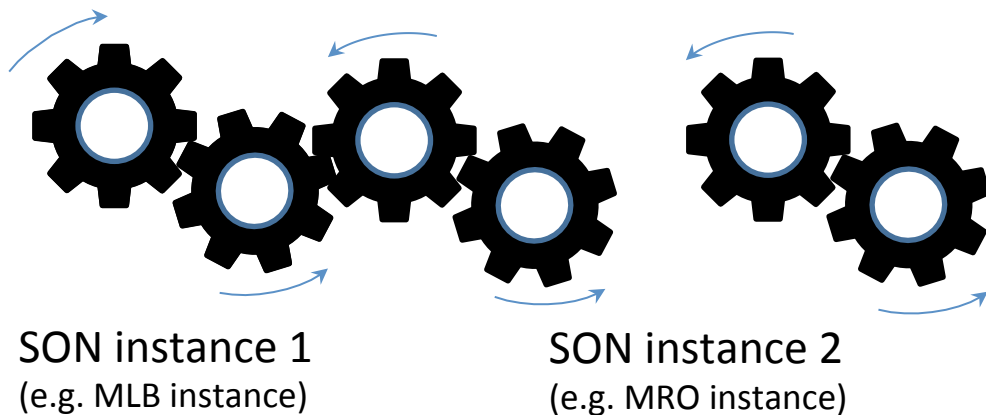


Presentation agenda:

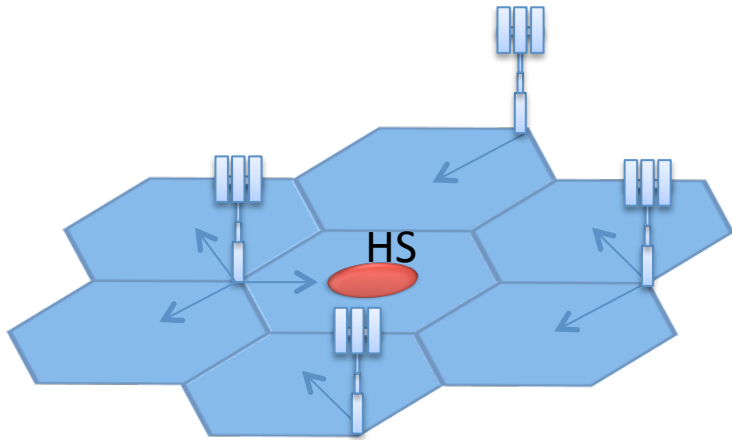
- Introduction
- System Description
- SON Coordination
- Simulation Results
- Conclusions and Future Work

Introduction to SON & SON Coordination

- SON functions are meant to automate network tuning (e.g. MLB, MRO, etc.) in order to reduce CAPEX and OPEX.
- A SON instance is a realization/instantiation of a SON function running on one or several cells.
- In a real network we may have several SON instances of different SON functions, **this can generate conflicts.**



System Description: MLB vs MRO



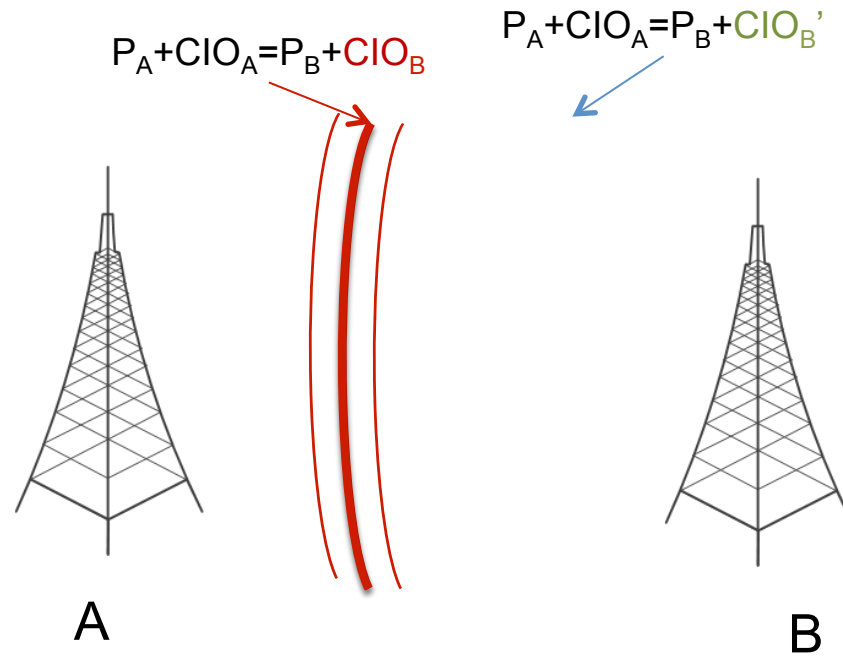
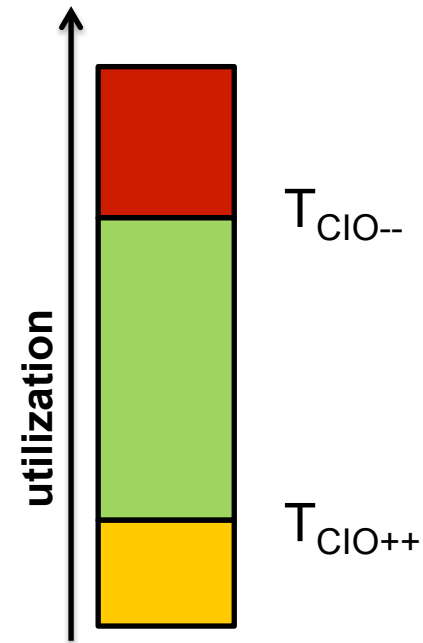
We consider:

- 2 SON functions: MLB and MRO
- a network segment of $N=7$ cells
- on every cell we have a MLB instance and a MRO instance
- one HotSpot (HS)
- FTP like traffic
- all SON instances are synchronized (time window 5 min)

System Description: MLB

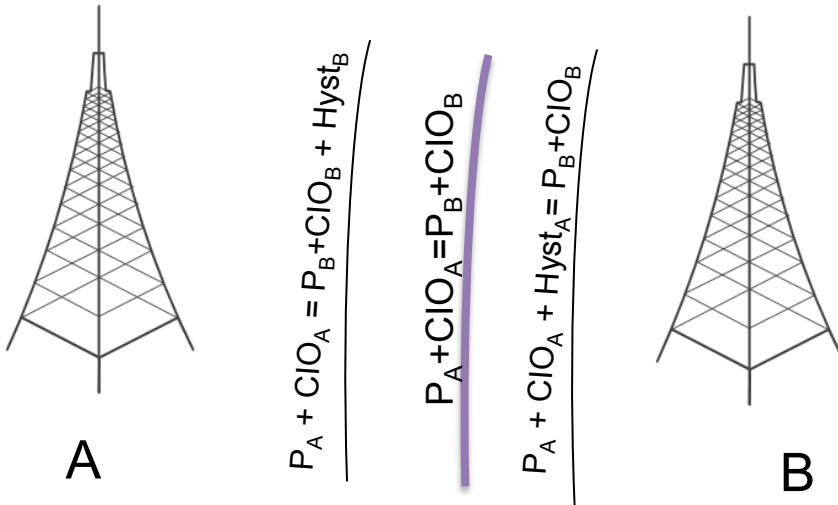
Looking at base station B:

- if(**utilization** > T_{CIO--}) \rightarrow CIO_{B--}
- if(**utilization** < T_{CIO++}) \rightarrow CIO_{B++} (for going back to the default configuration)
- else \rightarrow Relax (void)



CIO range (-12dB:0dB/ step-size 3dB)

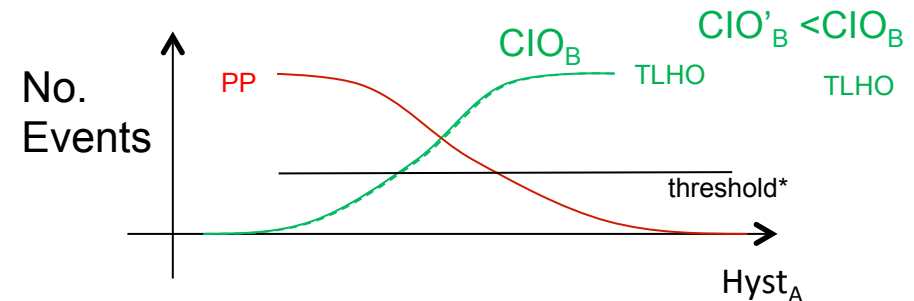
System Description: MRO



For Cell A:

• Too Late HOs (A→B)

- Ping-Pongs (A→B→*)
- Too Early HOs (A→B^(RLF)→A)
- Wrong Cell HOs (A→B^(RLF)→*)



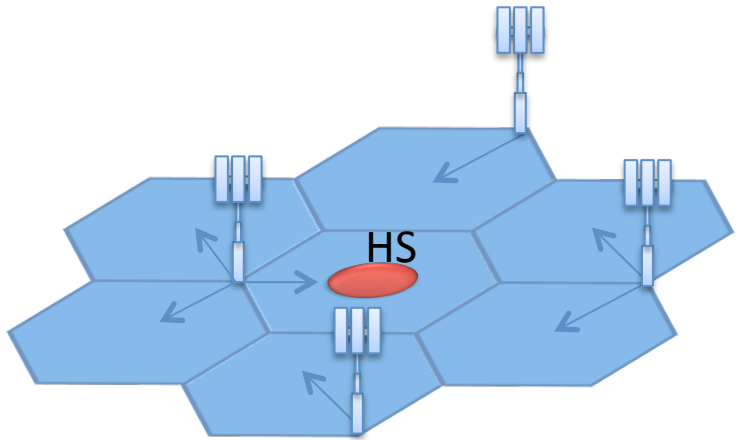
* For this example we considered the same threshold for all the parameters

MRO target: reduce the number of Too Late HOs, Too Early HOs, Wrong Cell HOs, Ping-Pongs

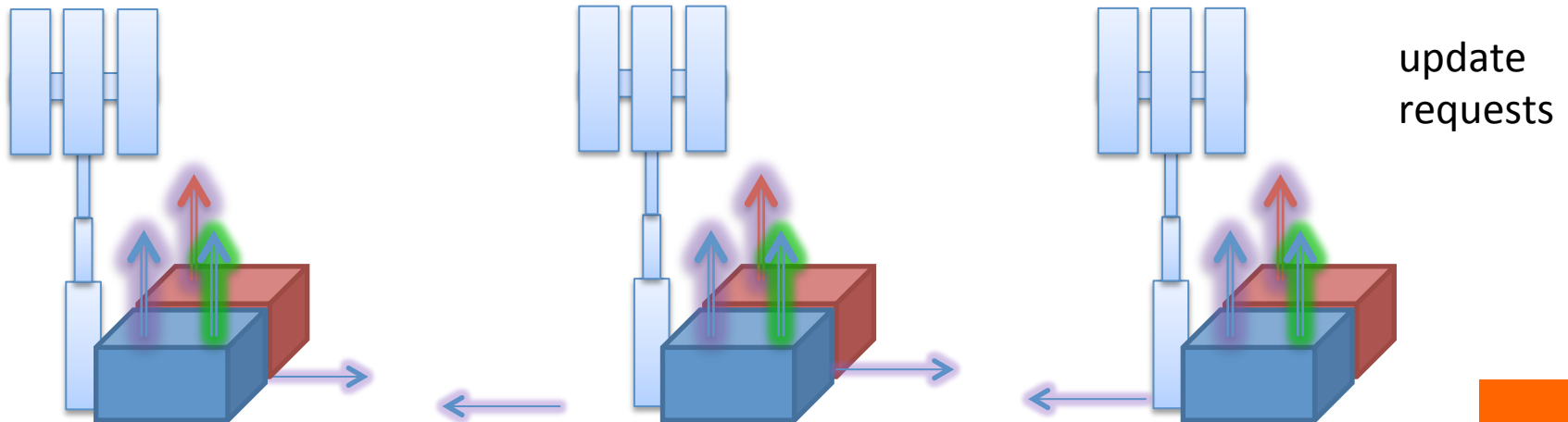
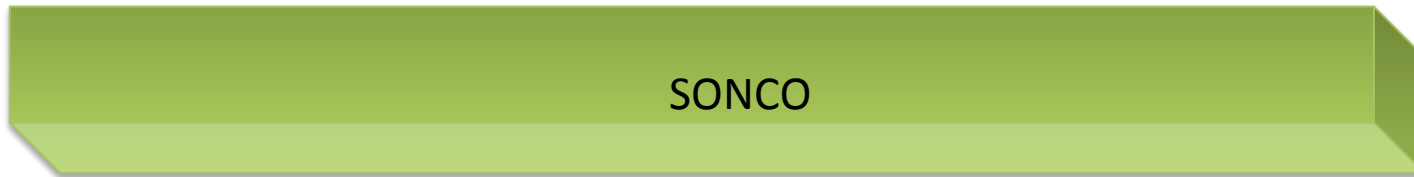
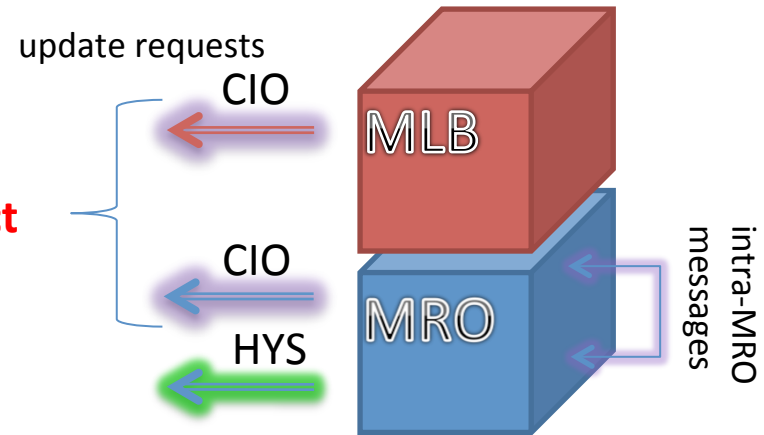
Example: Consider Cell A. as source for all the following events.

- to reduce the No. of Ping-Pongs we increase $Hyst_A$
- to reduce the No. of TooLateHOs we decrease $Hyst_A$
- to do both the above one solution is to first decrease the CIO of the neighbor towards which cell A has the biggest No. of TooLateHOs (assume it is cell B → CIO_B--). Afterwards we will most-likely increase $Hyst_A$.

SON Coordination



~~conflict~~ **conflict**



intra-SON messages

SON Coordination

- An update request contains
 - the parameter request: increase/decrease/maintain
 - an information on the criticalness of the request



Reinforcement Learning helps us learn from past decisions:

- create a state space that includes the CIOs of the cells(c)
- target: find the state that maximizes a “reward”
- the “reward” is a function of
 - the happiness indication contained in the update requests from the SON instances
 - weights associated to the SON functions by the operator

Function Init:

Initialize $W(c) = 0$ and $e(c) = 0$ for all $c \in \mathcal{C}$
Initialize $s = ((0, 0, 0), (0, 0, 0))$

Function SONCO:

Observe current state $s' = (c', u')$ and
calculate reward $r(s') = \rho(u')$

$\delta \leftarrow r + \gamma W(c') - W(c)$

$e(c) \leftarrow e(c) + 1$

for all $\tilde{c} \in \mathcal{C}$

$W(\tilde{c}) \leftarrow W(\tilde{c}) + \alpha \delta e(\tilde{c})$

if $a'^C = a^{C,opt}$ then $e(\tilde{c}) \leftarrow \gamma \lambda e(\tilde{c})$

else $e(\tilde{c}) \leftarrow 0$

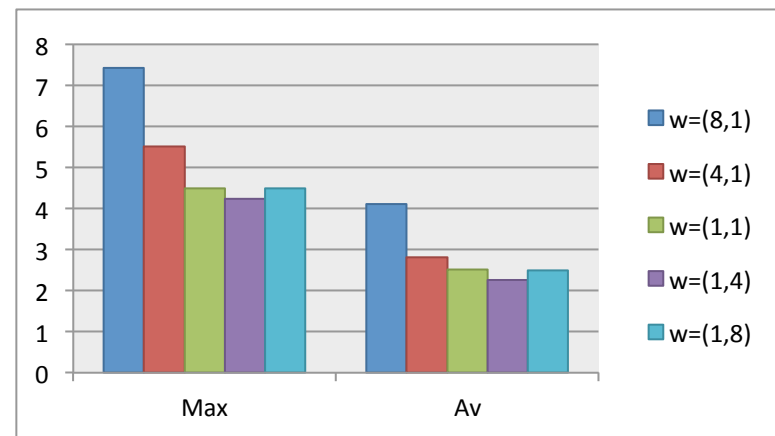
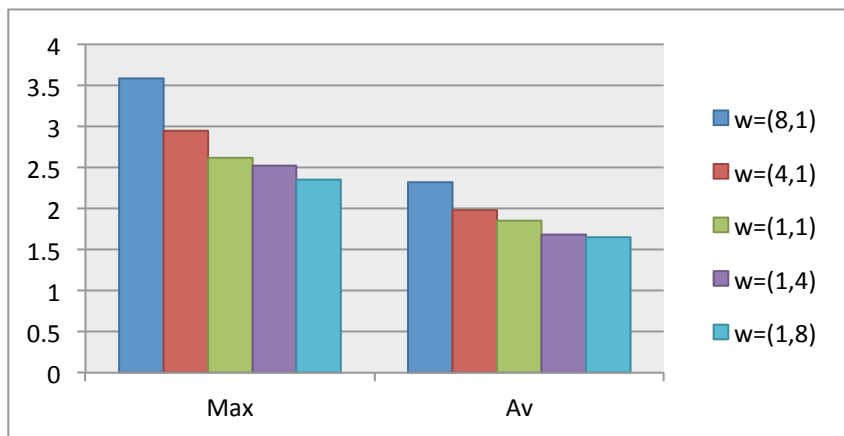
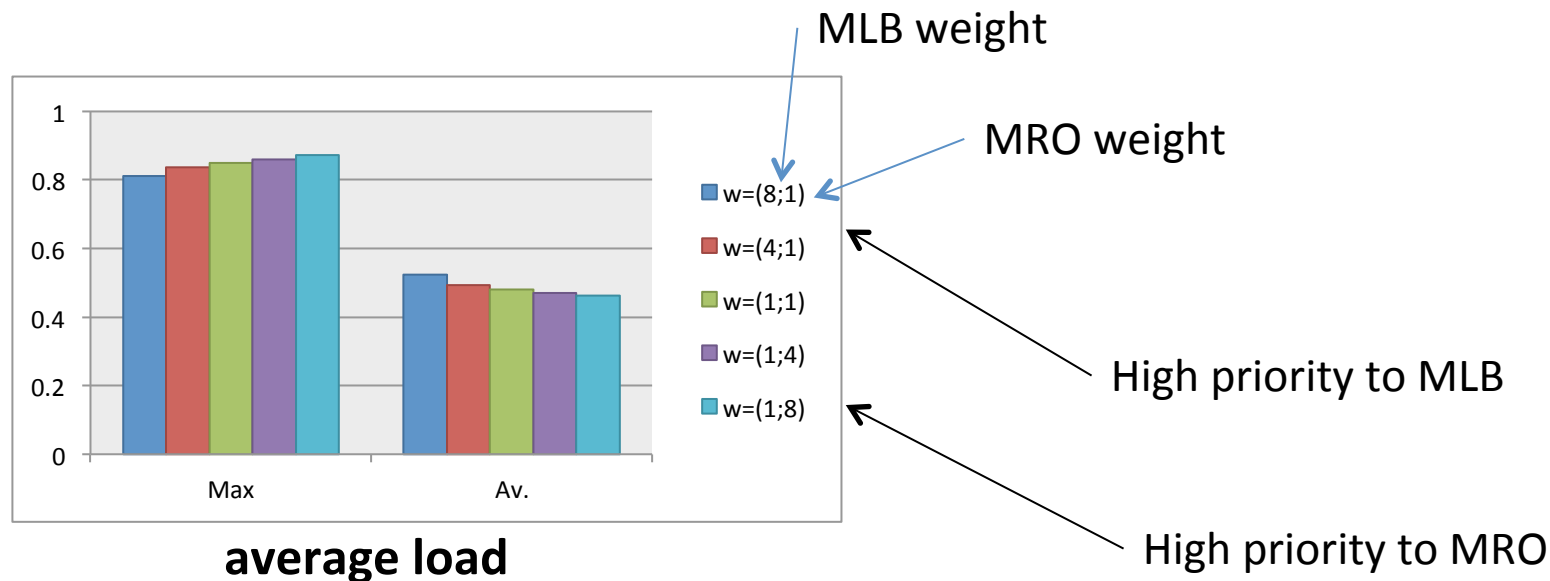
Choose action $a' = (a'^C, a'^H)$ using policy π ,

Calculate $a^{C,opt}$,

Take action a' ,

$s \leftarrow s' (\equiv (c, u) \leftarrow (c', u'))$

Simulation Results



(Maximum and average over all cells)

Conclusion and future work

- RL proves to have the qualities that allow us to tune the arbitration in favor of one or the other with respect to priorities/weights defined by the operator.
- By using a SON Coordinator we were able to intelligently decide when to accept/deny the requests of the SON instances in order to reach the desired tradeoff between the two SON functions w.r.t. to their corresponding targets (avoiding over-loads for MLB versus decreasing the number of connection failures and ping-pongs due to mobility for MRO).
- Simulation results show that the resulting KPIs reflect the operator priorities.
- Future work will focus on improving the scalability of our solution.

Questions

